

# Extended orbit model

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- Molecular Computational Anatomy : Unifying the Particle to Tissue Continuum via Measure Representations of the Brain, Miller, Tward, Trouvé

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- 2 Right-invariant subriemannian metrics
- 3 Including weight in the group

# Multi-scale LLDDMM

## Shape space

$\mathcal{Q} = \prod_{0 \leq l \leq L} \mathcal{Q}^l$  where  $\mathcal{Q}^l$  space of landmarks, varifolds, etc...

## Hierarchy of groups

We introduce extended group :

$$\mathbf{G}^k = \prod_{0 \leq l < L} \text{Diff}_{C_0^k}(\mathbb{R}^d)$$

with component-wise law  $\varphi \cdot \varphi' = (\varphi \circ \varphi')_{l \geq 0}$  and with component-wise action on  $\mathcal{Q} : \varphi \cdot \mathbf{q} = (\varphi \cdot q)_{l \geq 0}$

## RKHS

We consider a sequence of continuous embeddings

$V_0 \hookrightarrow \cdots \hookrightarrow V_{L-1} \hookrightarrow V_L \doteq C_0^m(\mathbb{R}^d)$  and  $\mathbf{V} = \prod_{0 \leq l < L} V_l$  equipped with the Hilbert norm defined by  $|\mathbf{v}|_{\mathbf{V}}^2 = \sum_{l=0}^{L-1} |v_l|_{V_l}^2$  for  $\mathbf{v} = (v_l)_{l=0}^{L-1} \in \mathbf{V}$ .

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# Variational problem

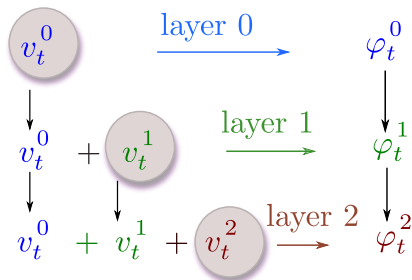


Figure – Hierarchical system of controls

$$d_{\mathbf{G}^k}(\mathbf{Id}, \varphi) = \inf_{\mathbf{u}, \dot{\varphi} = \mathbf{u}_t \circ \varphi} \frac{1}{2} \int_0^1 |\mathbf{A}\mathbf{u}_t|^2 dt \text{ with constraints}$$
$$\varphi(0) = \mathbf{Id}, \varphi(1) = \varphi$$

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## Extended framework

We introduce a family of groups  $\{G^l, l \in \mathbb{N}\}$  with following conditions

- (G.1)  $G^{k+1}$  is a subgroup of  $G^k$  with smooth inclusion
- (G.2) For  $l > 0$ , the inverse mapping on the restriction  $\text{inv} : G^{k+l} \rightarrow G^k$  is  $\mathcal{C}^l$
- (G.3) For  $l > 0$ , the induced multiplication

$$\begin{aligned} G^{k+l} \times G^k &\longrightarrow G^k \\ (g', g) &\longmapsto g' \cdot g \end{aligned}$$

is  $\mathcal{C}^l$ , and is also  $\mathcal{C}^\infty$  with regards to the first variable.

- (G.4) For  $l \geq 0$ , the induced left infinitesimal action

$$\begin{aligned} T_e G^{k+l} \times G^k &\longrightarrow TG^k \\ (u, g) &\longmapsto u \cdot g \end{aligned}$$

is a  $\mathcal{C}^l$  mapping, and  $\mathcal{C}^\infty$  with regards to the first variable.

# Subriemannian geometry

Let  $V \subset T_e G^{k+2}$  a Hilbert space. We define right-invariant metric on  $G^k$  induced by  $V$ .

Dynamic is given by

$$\begin{cases} g_0 = e \\ \dot{g}_t = u_t \cdot g_t = T_e R_{g_t}(u_t) \end{cases}$$

where  $u_t \in V$ . We define the energy of a path  $(g, u)$  as :

$$E(g, u) = \frac{1}{2} \int_I |u(t)|_V^2 dt$$

## Proposition

We have global existence and uniqueness of normal geodesics

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# Hamiltonian flow and Euler Poincaré equations

Hamiltonian

$$\mathcal{H}_{G^k} : \left\{ \begin{array}{l} TG^{k*} \times V \longrightarrow \mathbb{R} \\ (g, p, u) \longmapsto (p, u \cdot g) - \frac{1}{2}|u|_V^2 \end{array} \right.$$

Normal geodesics are solutions of the hamiltonian equations

$$\begin{cases} \dot{g} = \partial_p \mathcal{H}_{G^k}(g, p, u) \\ \dot{p} = -\partial_q \mathcal{H}_{G^k}(g, p, u) \\ \partial_u \mathcal{H}(g, p, u) = 0 \end{cases} \quad (1)$$

# Hamiltonian flow and Euler Poincaré equations

The momentum  $m_t = L_V u_t$  satisfies the equation :

$$\dot{m}_t + \text{ad}_{u_t}^*(m_t) = 0 \quad (2)$$

or equivalently the integrated form :

$$\frac{d}{dt} (m_t | \text{Ad}_{g_t}(v)) = 0 \quad (3)$$

which leads to the equation for  $g$  :

$$\dot{g} = K \text{Ad}_{g^{-1}}^*(m_0) \quad (4)$$

## Metric on Banach manifold

Let  $\mathcal{Q}_1$  and  $\mathcal{Q}_2$  Banach manifolds such that  $G^k$  acts on  $\mathcal{Q}_1$  and  $\mathcal{Q}_2$  with some nice hypotheses. Let  $(p_0^1, q_0^1, u_0^1) \in \mathcal{Q}_1 \times T\mathcal{Q}_1^* \times V$  and  $(p_0^2, q_0^2, u_0^2) \in \mathcal{Q}_2 \times T\mathcal{Q}_2^* \times V$  such that  $m_{\mathcal{Q}_1}(p_0^1, q_0^1) = m_{\mathcal{Q}_2}(p_0^2, q_0^2)$ . Then for all  $t \geq 0$ , we have

$$m_{\mathcal{Q}_1}(p_t^1, q_t^1) = m_{\mathcal{Q}_2}(p_t^2, q_t^2) \text{ and } q_t^1 = g_t \cdot q_0^1, q_t^2 = g_t \cdot q_0^2$$

with  $g_t$  satisfying the equation :

$$\dot{g}_t = Km_{\mathcal{Q}_i}(q_t, p_t) \cdot g_t$$

with  $i \in \{0, 1\}$

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# Action on varifold

We consider the space of  $d$ -varifolds as the space of Radon Borel measures  $\mathcal{M}(\mathbb{R}^d) = C_0(\mathbb{R}^d)'$ .

For  $\phi \in \text{Diff}(\mathbb{R}^d)$ ,  $\mu \in \mathcal{M}(\mathbb{R}^d)$ , we define  $\phi_*\mu$  as

$$\forall \omega \in C_0(\mathbb{R}^d), \phi_*\mu \cdot \omega = \mu \cdot \phi^*\omega$$

with  $\phi^*\omega$  the pullback of  $\omega$  by  $\phi$  defined by the relation

$$\forall x \in \mathbb{R}^d, \phi^*\omega(x) = |J\phi(x)|\omega(\phi(x))$$



# New action on varifolds

Instead consider semi-direct product :

$$H^k = \text{Diff}_{C_0^k} \ltimes C_0^{k-1}(\mathbb{R}^d, \mathbb{R}^{+*}).$$

where the group operation is given by  $(\varphi, \alpha) \cdot (\varphi', \alpha') = (\varphi \circ \varphi', \alpha \circ \varphi' \alpha')$

$\text{Diff}_{C_0^k}$  is embedded in  $H^k : i_H : \varphi \mapsto (\varphi, |J_\varphi|)$  and thus  $V$  induces right-invariant metric on  $H^k$

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## Co-adjoint variables

Let  $\varphi_0 \in G^k$  and  $p_0^H = (p_0^\varphi, p_0^\alpha) \in T_{i_H(\varphi_0)}^* H^k$  such that  $p_0^G = (di_H)^* p_0^H$ .  
Then for all time we have the following relation

$$p_t^G = (di_H)^* p_t^H \quad (5)$$

i.e.

$$p^G = p^\varphi - |J\varphi| (d\varphi^{-1})^* \nabla p^\alpha \quad (6)$$

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